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Optimizing Airspace Sectors for Varying Demand Patterns using Multi-Controller Staffing



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Outline



- ◆ Introduction
- ◆ Motivating Example
- ◆ Formulation of Mixed Integer Program
- ◆ Numerical Experiment
- ◆ Concluding Remarks

- ◆ Enroute sector boundary design should consider not only balancing controller workload but also efficient controller staffing.
- ◆ Traditional sectorization schemes input demand data aggregated over the planning horizon
 - ❖ E.g. one day, one month.
 - ❖ Variance in demand might result in inefficient usage of controller workforce.
- ◆ We propose new design concepts in clean-sheet sectorization:
 - ❖ Address demand variation across the planning horizon.
 - ❖ Consider efficient staffing plans for multi-period demand patterns.

- ◆ In the U.S., a common way to deal with temporary demand peaks in a sector is to use multiple controller teams.
 - ◆ E.g. a Radar-side controller plus a Data-side controller.

Number of Controllers by Function and Number of Aircraft Worked		
Function	Number of Aircraft Worked During 15-Minute Interval	Number of Controllers
High Altitude	0	0
Radar Sector	1 - 12	1
	13 - 17	2
	18 - 29	3
	30+	4

NOTE: For application, count aircraft worked for radar sector controller positions during current 15-minute interval. Count aircraft worked for A-side positions at +30 minutes from current 15-minute interval.



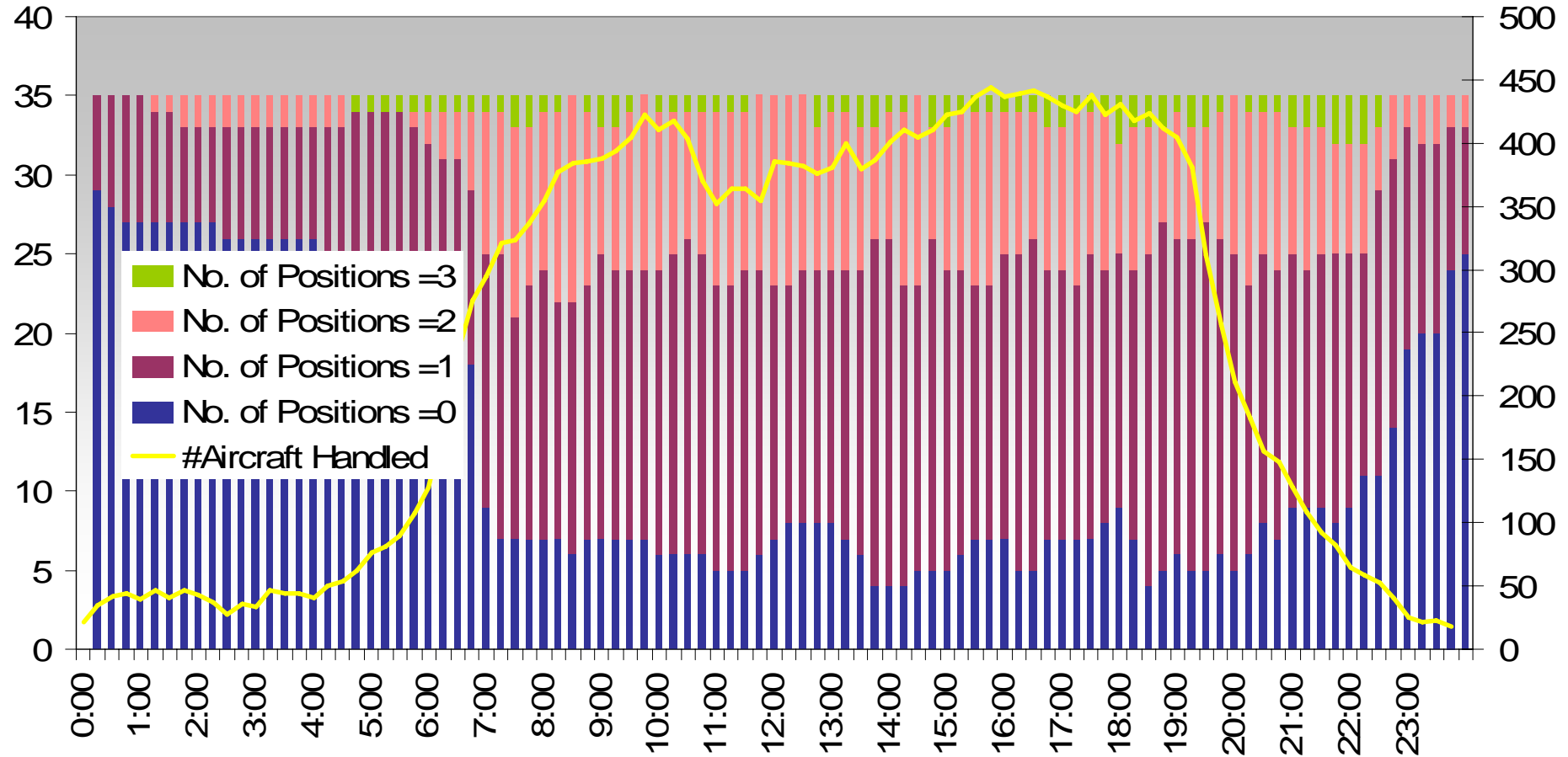
Staffing vs. Traffic



15-min Traffic vs. Controller Activity in ZNY (11/03/05)

No. of Sectors

No. of Aircraft





Enroute Air Traffic Controllers



◆ Functions:

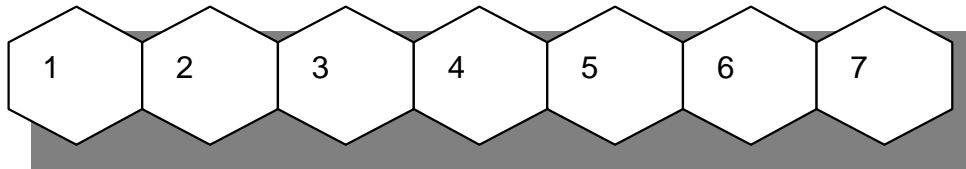
- ◆ F1 – Pilot communication/direction (verbal)
 - ◆ Tell pilot how to move.
- ◆ F2 – ATC coordination
 - ◆ E.g. neighboring controllers.
- ◆ F3 – Data processing
 - ◆ Flight strip marking and juggling.
- ◆ Common configuration: R-side (F1, F2) + D-side (F3)

◆ Scarce and expensive resources:

- ◆ The FAA will hire and train more than 15,000 controllers over the next decade.
- ◆ Controller labor costs have increased from \$82.98 per flight in FY1998 to \$137.81 per flight in FY2006.

Motivating Example

- ◆ Consider seven connected hex-cells to be grouped into 2 sectors



Only 6 ways to do this, since sectors must be contiguous!

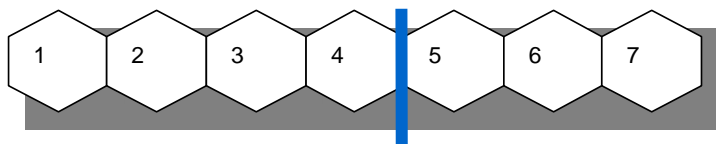
- ◆ Cell Demand Across Time Periods ($T = 1, 2, 3$):

Cell		1	2	3	4	5	6	7
Demand By Period	$T=1$	2	3	0	2	4	2	5
	$T=2$	5	3	3	1	5	3	5
	$T=3$	0	2	1	2	1	3	2
Sum:		7	8	4	5	10	8	12

- ◆ Compare two design concepts:
 - ◆ Aggregated Demand with Balancing Sector Workloads
 - ◆ Multi-period Demand with Awareness of Controller Capability

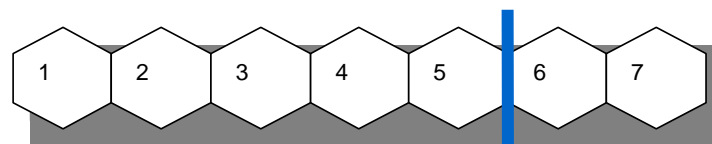
- Suppose that 1 controller can only handle up to 10 demand units in a time period.

Optimal Workload Balancing:



Controller Usage	Partition	
	[1,2,3,4]	[5,6,7]
T=1	1	2
Period T=2	2	2
T=3	1	1
Total	9	

Multi-period Model Considering Controller Capability:



Controller Usage	Partition	
	[1,2,3,4,5]	[6,7]
T=1	2	1
Period T=2	2	1
T=3	1	1
Total	8	

9 controller-hours required, versus 8 controller-hours

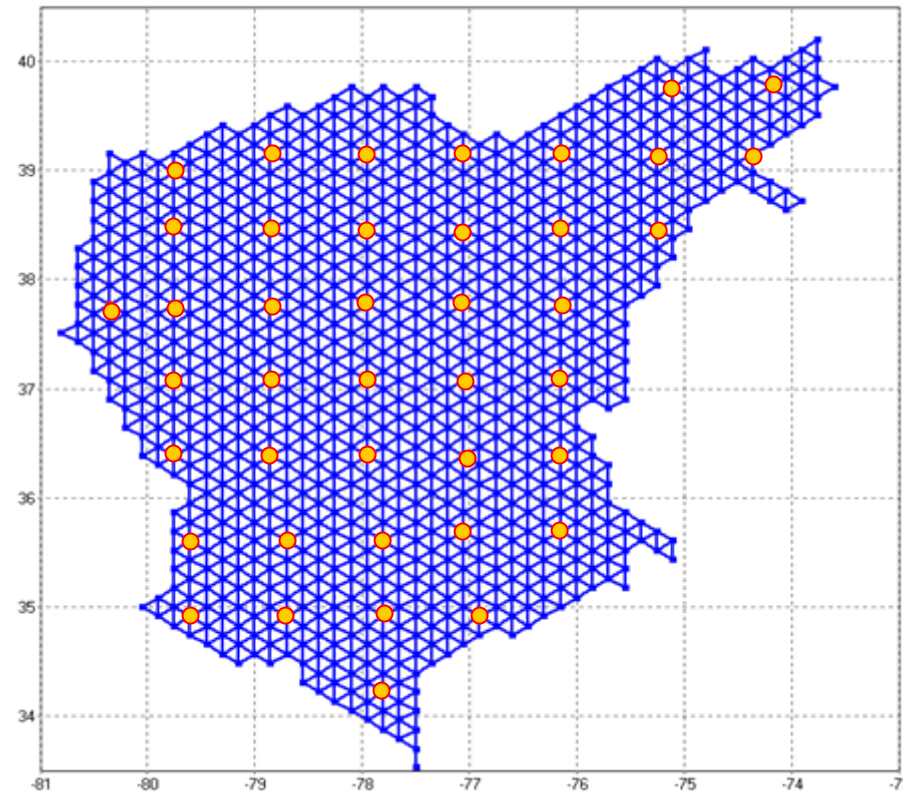
◆ Tile-and-group

- ◆ A mixed integer program is formulated to group the hex-cells.

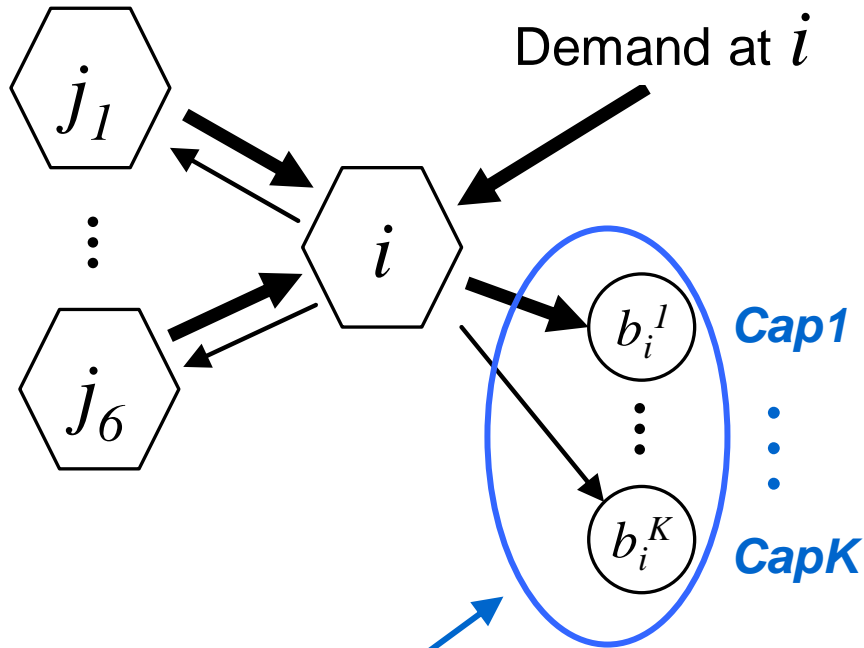
◆ Model Features:

- ◆ Time-varying demand patterns as input.
- ◆ Sector capacity changing over time by varying controller staffing.
- ◆ Sector shape in alignment with major traffic.

Underlying Network for Target Airspace

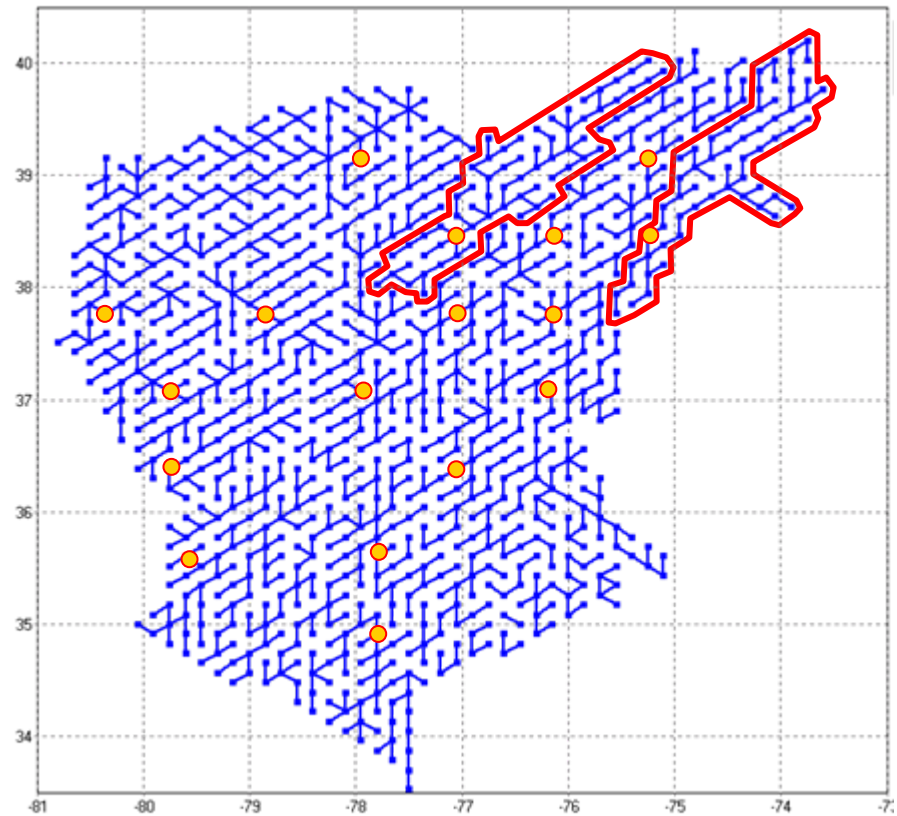


Network Structure at a Seed Node



Dummy nodes and links for sector capacity values.

Sample Solution for Target Airspace



A Variant of Fixed-Charged Network Design Problem (FCND)

Minimize $\sum_{\substack{i \in S, j \in B_i \\ t \in \{1, \dots, T\}}} f_{ij}^t p_{ij}^t + \mu \sum_{\substack{i \in \{1, \dots, I\} \\ j \in A_i \\ t \in \{1, \dots, T\}}} c_{ij}^t x_{ij}^t$

← Controller Cost
← Flow Alignment Penalty

Flow conservation

$$(1) \quad \sum_{j \in A_i} x_{ji}^t + d_i^t = \begin{cases} \sum_{j \in A_i} x_{ij}^t & \text{for all } i \notin S, t \in \{1, \dots, T\} \\ \sum_{j \in A_i \cup B_i} x_{ij}^t & \text{for all } i \in S, t \in \{1, \dots, T\} \end{cases}$$

One Outbound Flow

$$(2) \quad \sum_{j \in A_i} q_{ij} = \begin{cases} 1 & \text{for all } i \notin S \\ 1 - \sum_{j \in B_i} p_{ij}^t & \text{for all } i \in S, t \in \{1, \dots, T\} \end{cases}$$

Link Selection

$$(3) \quad x_{ij}^t \leq M_{ij} q_{ij} \quad \text{for all } i \in \{1, \dots, I\}, j \in A_i, t \in \{1, \dots, T\}$$

Controller Staffing Selection

$$(4) \quad M_{i, b_i^{k-1}} p_{i, b_i^k}^t \leq x_{i, b_i^k}^t \leq M_{i, b_i^k} p_{i, b_i^k}^t \quad \text{for all } i \in S, k \in \{1, \dots, K\}, t \in \{1, \dots, T\}$$

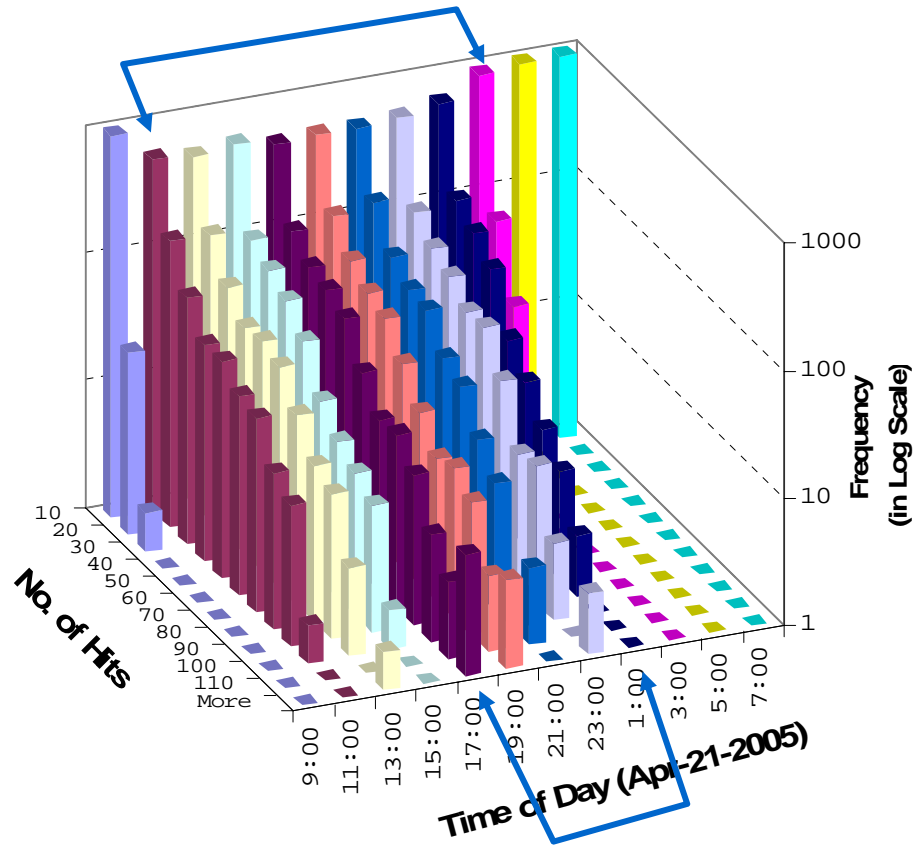
◆ Basic Settings:

- ❖ ZDC airspace is translated into a network of 1043 nodes, 2961 links, and 41 seed nodes.
- ❖ 2 choices of sector capacity values are considered
 - ◆ I.e. at most 2 controller positions per sector.

◆ Experiments

- ❖ High Variation Case (4 periods x 4 hours)
- ❖ Low Variation Case (4 periods x 2 hours)

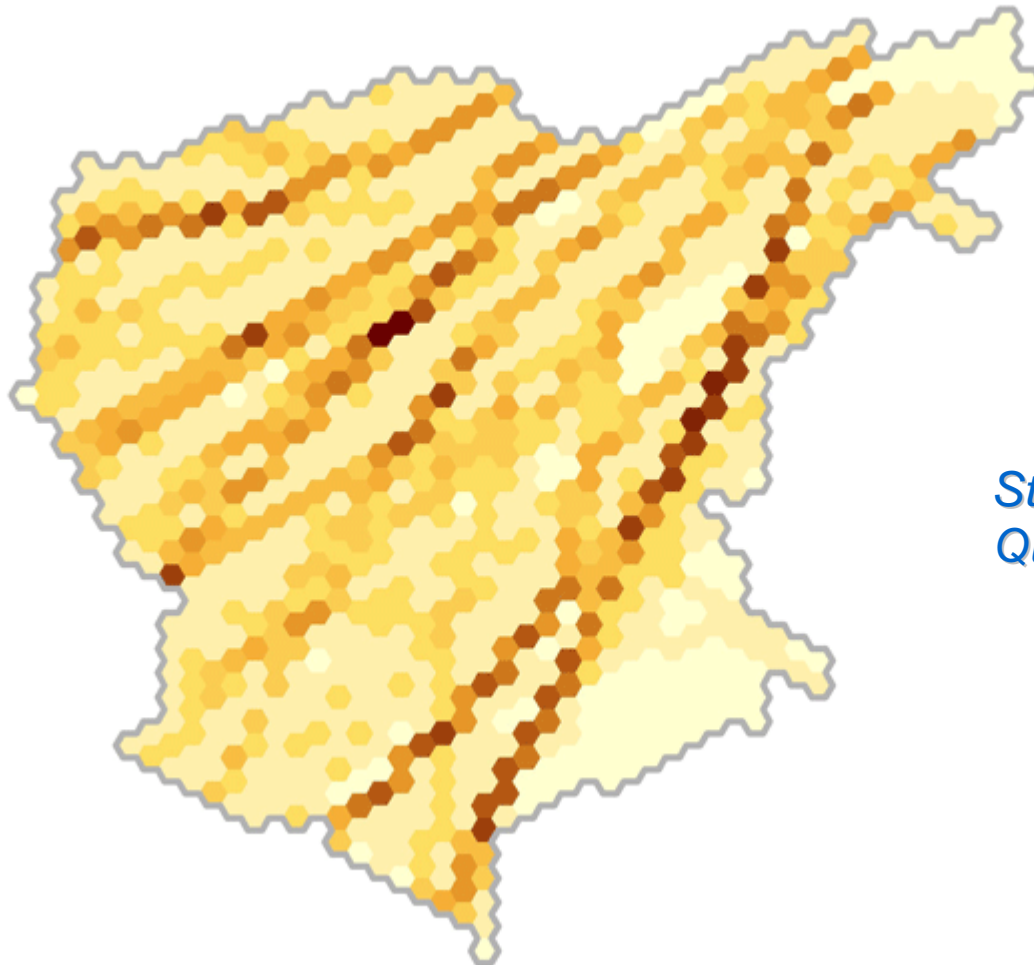
High Demand Variation Case, 11:00 – 03:00



Low Demand Variation Case, 17:00 – 01:00

ZDC Demand Variation on April 21 2005

11:00-15:00



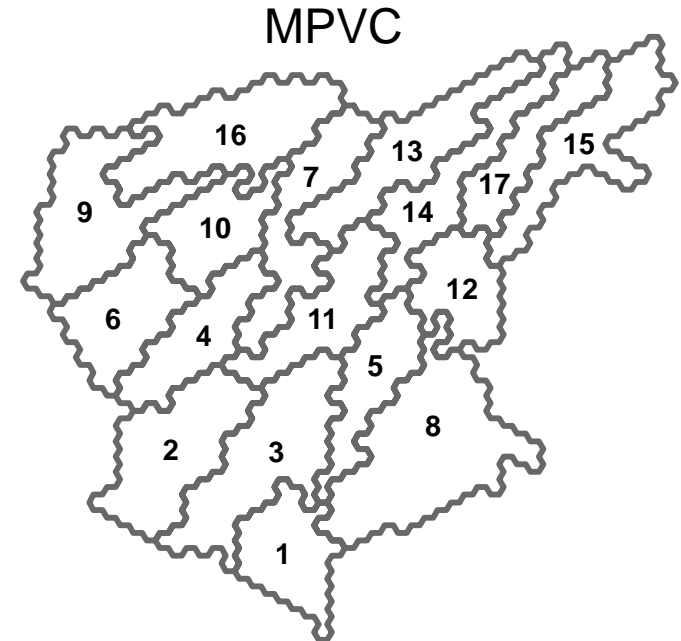
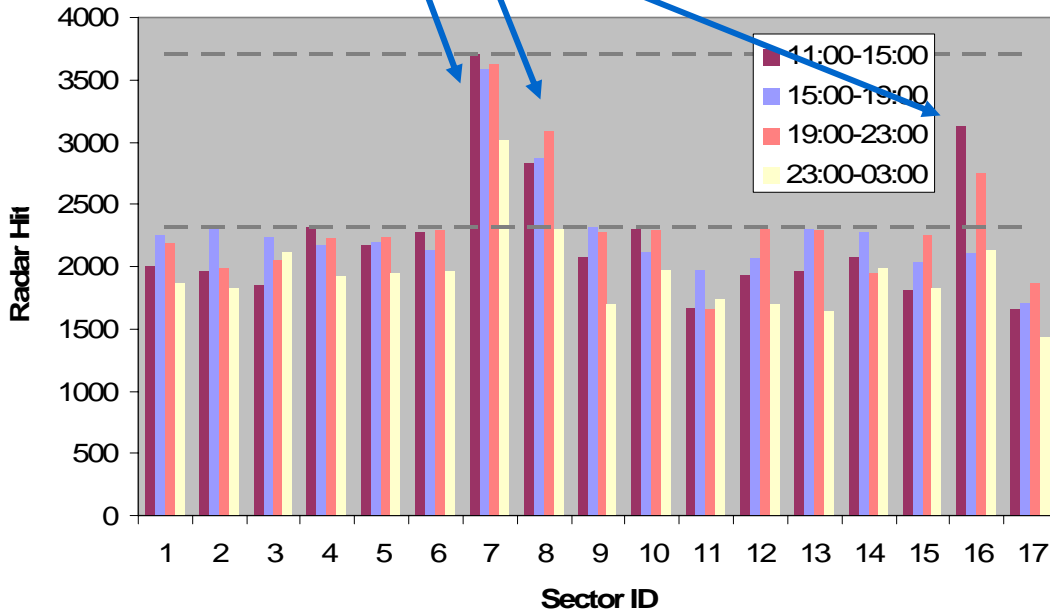
*Strong directional patterns.
Quiet at midnight.*



MPVC Results (High Demand Variation Case)



Two controller team required.



Resulting No. of Sectors	Resulting No. of Controller Shifts				Capacity Assumed	
	11:00	15:00	19:00	23:00	Using 1 Position	Using 2 Positions
	/ 15:00	/ 19:00	/ 23:00	/ 03:00		
17	20	19	20	18	2315	3704

*Total Controller Hours:
(20+19+20+18)×4 = 308*

- ◆ Yousefi et al (2007) developed a workload balancing model with the following characteristics:
 - ❖ Optimizing sector boundaries to align with traffic.
 - ❖ Workload deviation among sectors is controlled within a tolerance value.
 - ❖ Number of sectors is set as an input value.
 - ❖ Demand is aggregated across the planning horizon.
- ◆ By imposing additional constraints and set $T=1$ and $K=1$, we can obtain YMIP results:

$$\sum_{i \in S, j \in B_i} p_{ij}^t = \text{Desired No. of Sectors}$$

$$p_{i,b_i}^t (1 - \gamma) W_{\text{target}} \leq x_{i,b_i}^t \leq p_{i,b_i}^t (1 + \gamma) W_{\text{target}} \quad \text{for all } i \in S$$

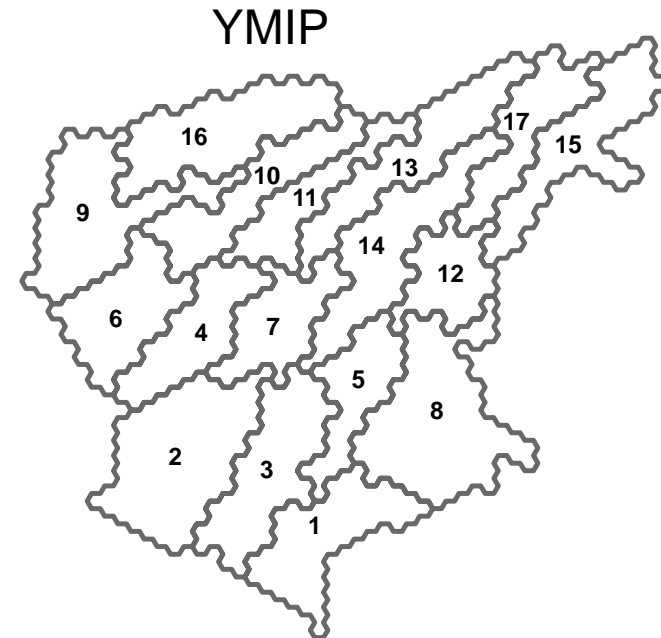
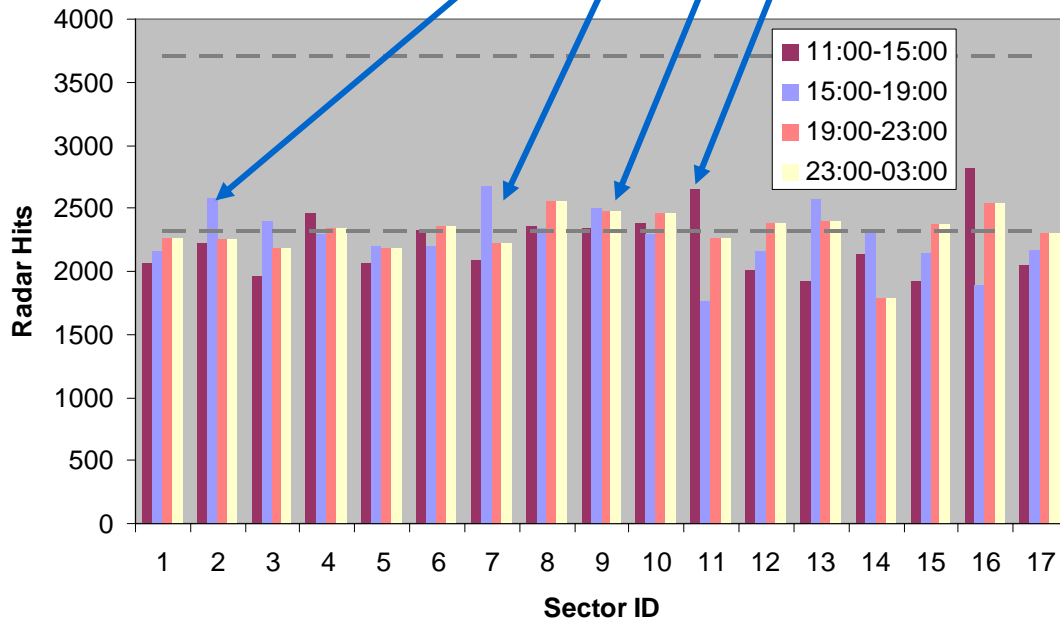


YMIP Results (High Demand Variation Case)



All bars over dashed line invoke a 2-controller team

and so on...



Resulting No. of Sectors	Resulting No. of Controller Shifts				Capacity Assumed	
	11:00 / 15:00	15:00 / 19:00	19:00 / 23:00	23:00 / 03:00	Using 1 Position	Using 2 Positions
17	24	24	26	17	2315	3704

Total Controller Hours:
(24+24+26+17)×4 = 364

18% more in controller hours than MPVC result!



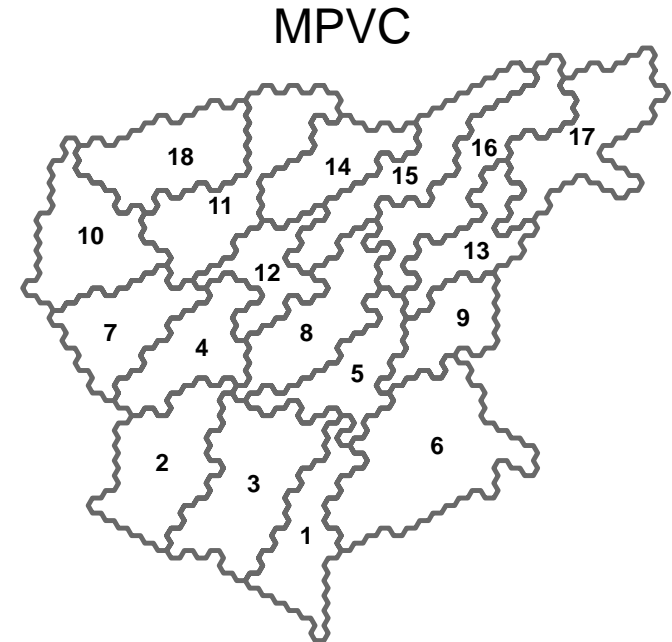
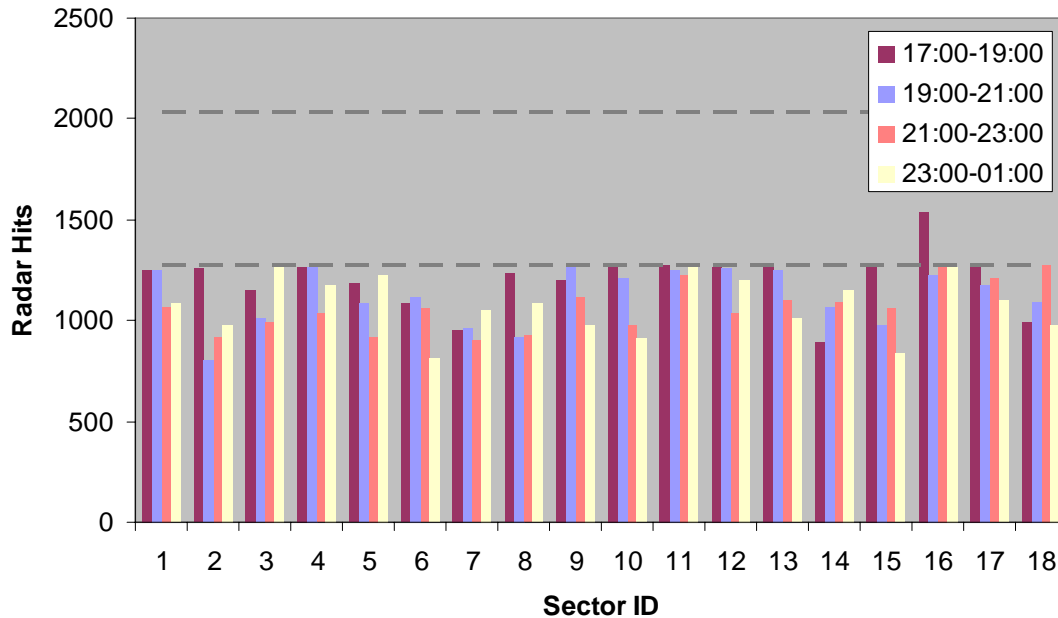
Notes on High Demand Variation Case



- ◆ Unawareness of controller team sizes might create an inefficient design (e.g. second controller needed but not well utilized).
- ◆ Different design strategies of implementing YMIP:
 - ❖ Limiting the target workload under 1-controller threshold:
 - ◆ In this instance, YMIP requires 20 sectors and thus 320 controller hours (still higher than the MPVC result).
 - ❖ Applying YMIP for individual periods:
 - ◆ Periodic reapplication probably requires wholesale boundary changes during “the heat of battle”.



MPVC Results (Low Demand Variation Case)



Resulting No. of Sectors	Resulting No. of Controller Shifts				Capacity Assumed	
	17:00 / 19:00	19:00 / 21:00	21:00 / 23:00	23:00 / 01:00	Using 1 Position	Using 2 Positions
18	19	18	18	18	1272	2035

When demand is steady, creating two 1-controller sectors is more efficient than one 2-controller sector!

Total Controller Hours: (19+18+18+18)×2 = 146



Numerical Results Summary



Test Case	High Demand Variation		Low Demand Variation	
<i>Planning Horizon</i>	16 Hrs		8 Hrs	
<i>Duration per Period</i>	4 Hrs		2 Hrs	
<i>Model (MIP)</i>	MPVC	YMIP	MPVC	YMIP
<i>Design Objective</i>	Minimize no. of controller shifts and sectors; Minimize flow alignment cost	Balance workload among sectors; Minimize flow alignment cost	Minimize no. of controller shifts and sectors; Minimize flow alignment cost	Balance workload among sectors; Minimize flow alignment cost
<i>Required Controller-hours</i>	308	364	146	162
<i>Avg. Flight Dwell Time</i>	8.0	8.5	7.8	8.2
<i>BalDev+</i>	59.1%	5.0%	18.8%	5.0%
<i>BalDev-</i>	-23.7%	-5.0%	-13.4%	-5.0%



Conclusion Remarks



- ◆ We extend the scope of workload-balancing sectorization techniques in the literature to allow for imbalances that align with controller team sizes.
- ◆ Multi-controller positions are used to address demand variation over multiple periods.
- ◆ Multi-period design also avoids frequent and disruptive wholesale resectorization throughout the day.
- ◆ Our work can be extended by taking weekday or seasonal effects into account.

- ◆ Quality sector design has multi-objectives. There are other factors to be considered (e.g. intersection and flow proximity to sector boundary).
- ◆ The linkage between controller staffing and sector capacity values should be further explored.
- ◆ The running time of MPVC increases with the number of periods and the size of the underlying network. More efficient solution method is needed.
- ◆ Further extensions might include:
 - ◆ Non-controller resource constraints on sector capacity (e.g. radio frequencies).
 - ◆ The uncertainty of capacity estimates and demand forecasts.



Thank you!

